

NRG Rocket

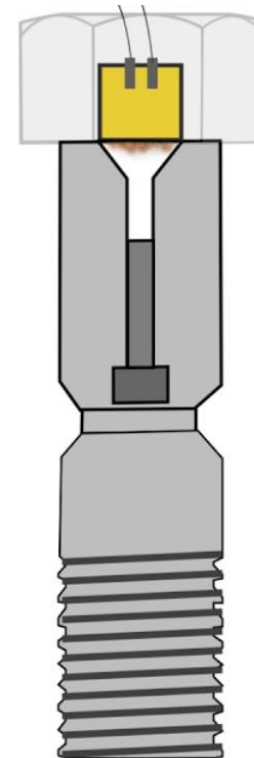
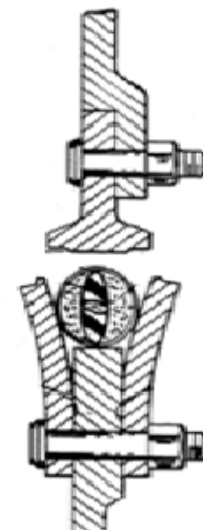
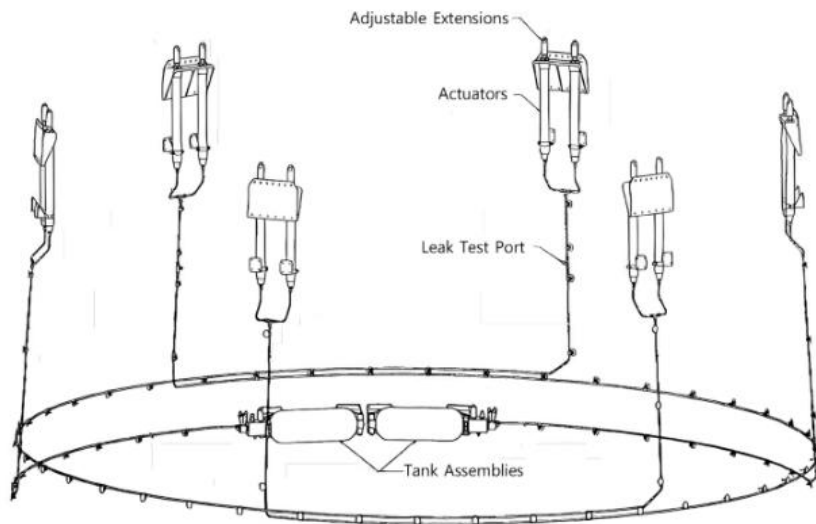
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Background, Need, Why Northrop Grumman, and Stakeholder Impact

- Background & Traditional Method
 - Rockets traditionally use frangible joints for stage separation due to their simplicity and reliability.
 - Example: Space Shuttle used frangible joints for stability on the launch pad, with controlled explosives as a backup for separation.
- Challenges with Frangible Joints
 - Risk of failure – If the explosive fails, stages remain attached, jeopardizing the mission.
 - High shock loads – Potential to damage sensitive spacecraft equipment.
 - Single-use system – Requires purchasing new explosive material for each launch.
- Magnetic Separation System: A Better Alternative
 - No explosives required – Increases safety and reliability.
 - Reduced shock loads – Protects delicate onboard instruments.
 - Reusable – Lowers operational costs and supports reusable rocket designs.
- Why Northrop Grumman?
 - Pioneered magnetic separation for rockets to enhance cost-effectiveness and reusability.
 - Eliminates need for explosive charges, reducing material costs.
 - Aligns with modern spaceflight goals – safer, more sustainable, and cost-efficient solutions.

Other Types of Separation Devices

- Frangible Joints
- Pneumatic Stage Separation System
- Explosive Bolts



Project Description

- This project revolves around creating a magnetic separation device for a supersonic rocket that will reach a maximum altitude of 50,000 [ft]
- Northrop Grumman is sponsoring this project, and it is important because magnetic separation in rockets can be a much cheaper, safer, and more effective alternative to present devices
- 80% of time will be allocated to separation device research
- 20% of time will be allocated to other parts of the rocket

Quality Function Deployment (QFD)

		Engineering Requirements									1 - Weak 3 - Moderate 9 - Strong			Benchmark Competitors
Customer Needs	Customer Weights	Total Weight	Total Drag Force	Thrust Force	Magnetic Force	Spring Force	Magnetic Fields	Testing	Altitude	Velocity				
Reusability	3	6		3	9						A	B	C	
Workability	5			6	9		9		3	3		B	AC	
Magnets	5	6	6	6	9	6	9	9						
Two-Stage Separation	5	6	9	9	9	6	9	9	6				ABC	
Stability	3	9	9	9				3		9		AB	C	
Faster than Mach 1	4	9	6	9				3	6	9			ABC	
30,000 ft altitude	5	6	6	9				3	9	9			ABC	
Test Launch	4						9	9	9	9				
Actual Launch	5	9					9	9	9	9				
Technical Requirement Units		N	N	N	N	N	N/A	N/A	kft	m/s				
Technical Requirement Targets		445	<1000	4200	>Spring Force		N/A	N/A	N/A	N/A				
Absolute Technical Importance		216	156	222	162	60	216	207	195	204				
Relative Technical Importance		2	8	1	7	9	2	4	6	5				

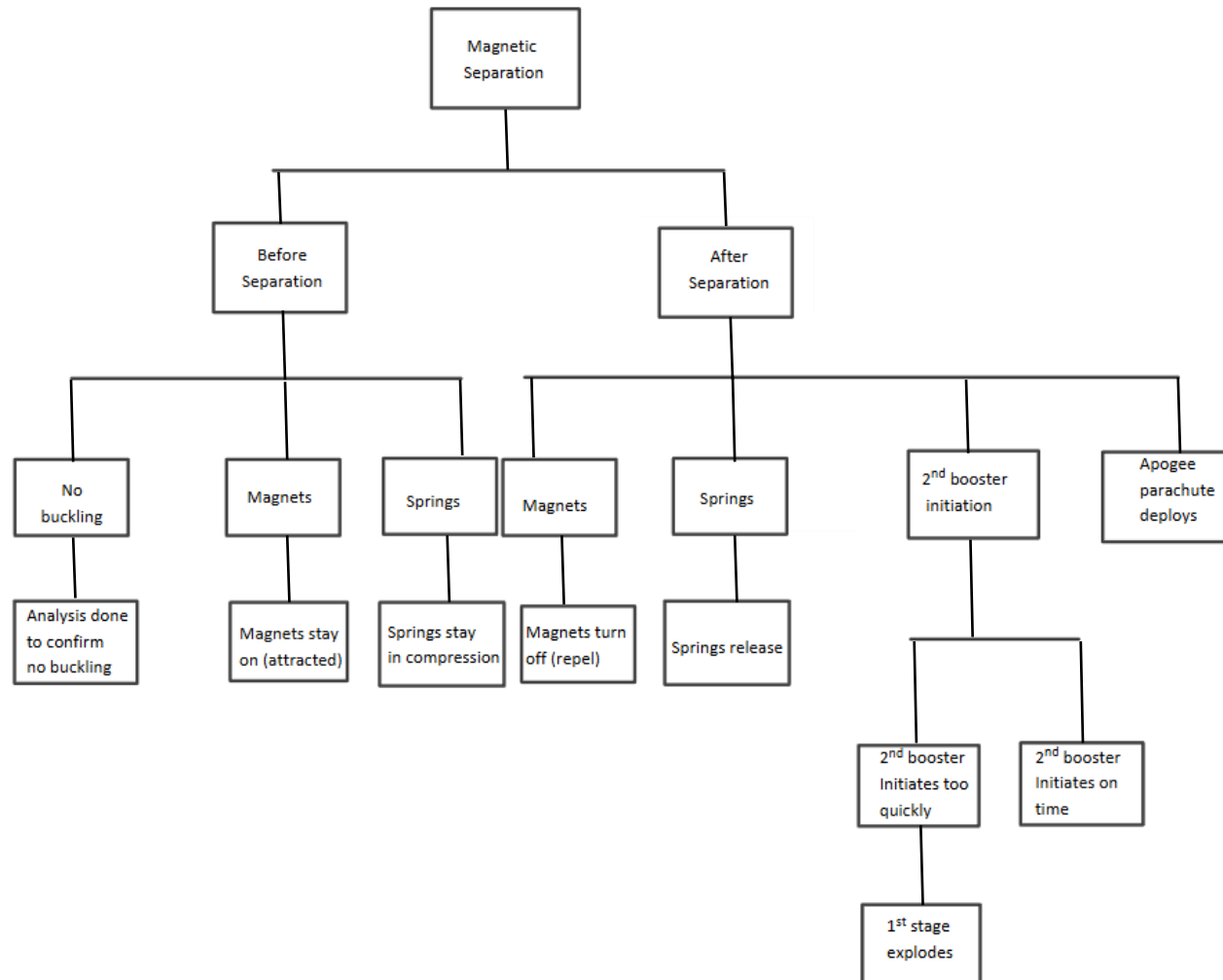
Separation Types	
A	Mechanical Separation
B	Pyrotechnic Separation
C	Aerodynamic Separation

9 = Strong
3 = Moderate
1 = Weak
Blank = No Relationship

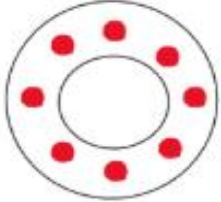
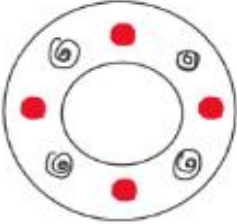
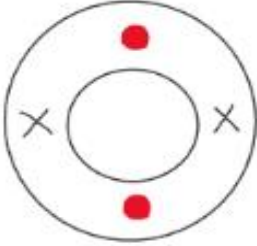
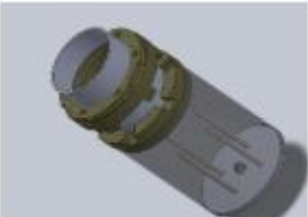
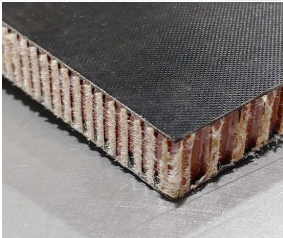
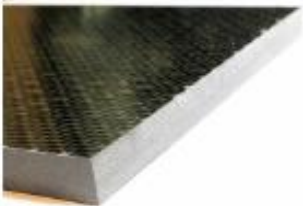
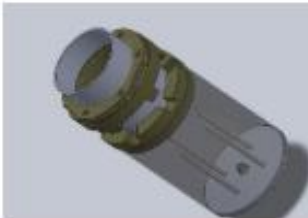
Black Box Model



Detailed Decomposition Model



Concept Generation Morphological Matrix

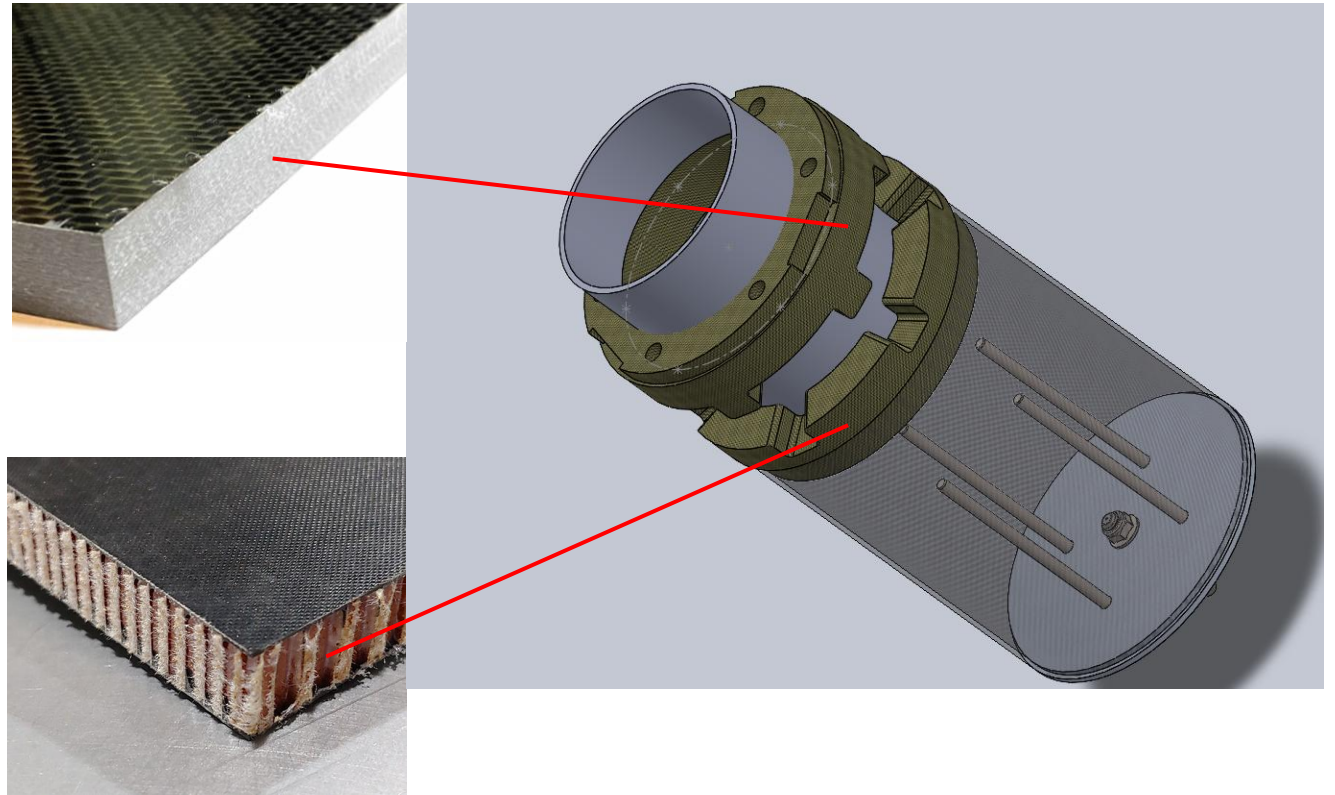
Subsystem:	1	2	3
Dispersion:			
Material composition:		 	 

KEY:

- = magnet
- @ = spring
- X = black powder charge

Concept Generation: Fully Carbon Fiber & Honeycomb Core

- These concepts were generated on improving from the current aluminum design.
 - Fully Carbon Fiber Base
 - Honeycomb core wrapped in Carbon Fiber
- Advantage Fully Carbon
 - High strength in Compression and Tension
- Disadvantage of Fully Carbon
 - Weight
 - Cost of Materials
- Advantage of Honeycomb Core
 - Light and reduce of carbon fiber
 - High Compression Load
- Disadvantage
 - Manufacturing Challenges
 - Honeycomb core lacks in tension



Factor of Safety Table

★ ASSUME MAXIMUM DRAG OF 1000 LBS ★

[2]

Material/Component:	Type of Loading:	Factor of Safety (FoS):
Aluminum/Separation device	Static	N/A
Aluminum/Separation device	Dynamic/Compressive	18.15
Carbon Fiber/Separation device	Static	N/A
Carbon Fiber/Separation device	Dynamic/Compressive	39.46
Carbon Fiber & Honeycomb Core/Separation device	Static	N/A
Carbon Fiber & Honeycomb Core/Separation device	Dynamic/Compressive	TBD

Theoretical Velocity and Height; Given

- Assumption
 - No Air Resistance
- First Stage
 - Avg. Thrust: 3336.165 N
 - Mass of Rocket: 46.81 kg
 - Initial Velocity: 0
 - Time: 4.1 s
- Second Stage
 - Mass of Rocket: 23.405 kg
 - Time: 4.1 s

N3300R-PS *Redline*™

RMS hardware required: 98mm aft closure, 98mm forward closure, 98mm forward seal disk, 98/15360 case.

Also requires separately packaged 1 x P/N 03040-6 phenolic liner and 6 x P/N 03618-6 propellant grains.

Motor Specifications

Total impulse: 13,410 N-sec (3,015 lb-sec)

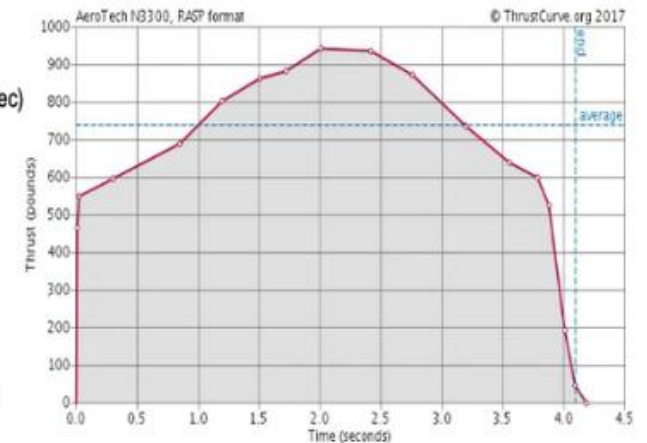
Burn time: 4.1 sec

Peak thrust: 950 lbs (4,226 N)

Delay time: Plugged with smoke

Propellant wt.: 7,338 grams (16.2 lb.)

Loaded wt.: 12,054 grams (26.6 lb.)



P/N 14330P • Certified by the Tripoli Rocketry Association (TRA) • Made in U.S.A. • www.aerotech-rocketry.com
AeroTech Division, RCS Rocket Motor Components Inc., 2113 W. 850 N.St., Cedar City, UT 84721

Theoretical Velocity and Height

- First Stage

- Avg. Thrust – $mg = ma$
- $a = 61.46 \text{ m/s}^2$
- $V_{f1} = V_o + (at)$
 - $V_{f1} = 251.986 \text{ m/s}$
- $Y1 = Y_o + V_o t + 0.5at^2$
 - $Y1 = 1694.78 \text{ ft}$
- $M1 = 0.734$
 - Subsonic
 - $M < 1$

- Second Stage

- Avg. Thrust – $mg = ma$
- $a = 132.73 \text{ m/s}^2$
- $V_{f1} = V_o + (at)$
 - $V_{f2} = 796.179 \text{ m/s}$
- $Y2 = Y1 + V_{f1}t + 0.5at^2$
 - $Y2 = 8744.42 \text{ ft}$
- $M2 = 2.32$
 - Supersonic
 - $M > 1$

- Max Height

- $V_f = 0$ at max height
- $V_f = V_o + (-g)t$
- $Y3 = Y2 + V_{f2}t + 0.5(-g)t^2$
 - $Y3 = 114,744 \text{ ft}$

Theoretical Velocity and Height

- Very conservative calculation
 - What's not included
 - Drag force
 - Area
- What's Next?
 - New set of analysis taking in account of drag force
 - RASAero II Simulations

$$ma = F_T - mg - \frac{1}{2} \rho a^2 t^2 \left[C_{D_{fin}} A_{D_{fin}} + C_{D_{skin}} A_{skin} + C_{D_{nose}} A_{nose} \right]$$

Assuming

1. Constant Mass
2. Constant Air Density
3. Constant Gravity
4. Avg. Thrust Force is Constant

Adriana's Analysis – Nose Cone Drag Force

- L-D Von Karman Haack Series Nose Cone shape

- The shape of the cone is found by calculating C
- Goal is to have minimum drag – range: 0-0.66

- Haack Series shape equation

➤ $\theta = \cos^{-1}\left(1 - \frac{2x}{L}\right)$

➤ $y = \frac{R}{\sqrt{\pi}} \sqrt{\theta - \frac{\sin(2\theta)}{2} + C \sin^3(\theta)}$

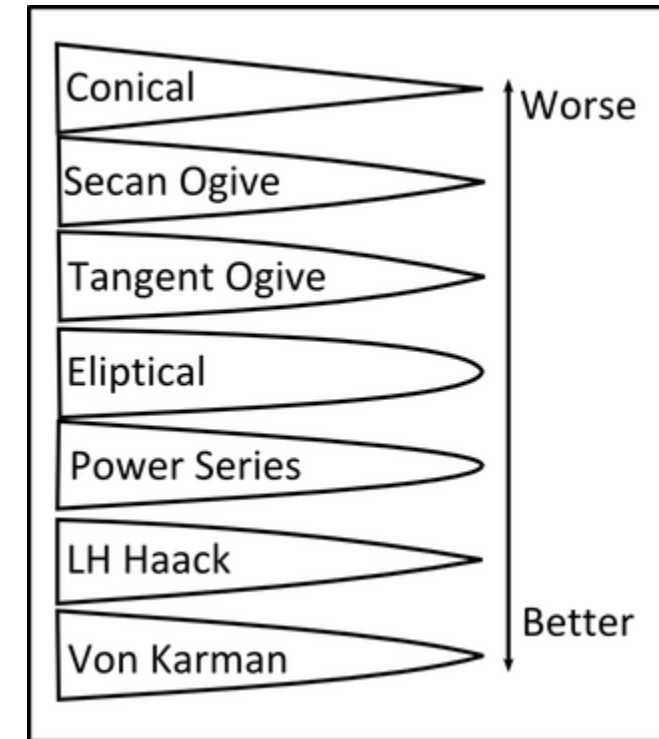
- C = 0; minimum for given length and diameter

➤ $D = Cd \frac{\rho V^2}{2} A ; A = \pi r^2, r=3.085in$

- **D : Drag Force** = 5.4 pounds
- **Cd : Drag Coefficient** = 0.05
- **ρ : Density** = 0.0408 pound per foot³
- **V : Velocity** = 2611 ft/s
- **A : Reference Area** = 2.4108 ft/s²

- Assumptions based on design

- Nose cone drag will be minimal
- Optimal for performance– speed and weight



Lee's Analysis (Fin Drag)

```
1 % Rocket Fin Drag Calculation
2 % Author: Lee Freytes Colón
3 % Date: March 2, 2025
4
5 clc; clear; close all;
6
7 %% Given Data
8 rho = 0.0880349; % Air density at 20,000 ft (kg/m^3)
9 v = 686; % Velocity in m/s (Mach 2)
10 Cd = 0.005; % Drag coefficient
11 A_single = 0.01677; % Area of one fin in m^2
12 num_fins = 6; % Number of fins
13
14 %% Total Area Calculation
15 A_total = num_fins * A_single;
16
17 %% Drag Force Calculation for One Fin
18 D_single = 0.5 * rho * v^2 * Cd * A_single;
19
20 %% Total Drag Force Calculation
21 D_total = 0.5 * rho * v^2 * Cd * A_total;
22
23 %% Display Results
24 fprintf('Total fin area: %.5f m^2\n', A_total);
25 fprintf('Drag force for one fin: %.2f N (0.390 lbf)\n', D_single, D_single * 0.224809);
26 fprintf('Total drag force for six fins: %.2f N (2.343 lbf)\n', D_total, D_total * 0.224809);
```

Total fin area: 0.10062 m²

Drag force for one fin: 1.74 N (0.390 lbf)

Total drag force for six fins: 10.42 N (2.343 lbf)

- Fin drag is proportional to surface area, velocity squared, and air density.
 - Reducing drag is essential for improving rocket efficiency and stability at supersonic speeds.
 - Future improvements could focus on refining fin shapes, using lower-drag materials, or adjusting fin positioning to minimize resistance.
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Stonn's Analysis: Skin Friction Drag Analysis

- Skin Drag at Mach 2 (30,000 ft)
- Drag Forces
 - $D_{Total} = 44.1 \text{ lbf}$
 - $D_{Stage 1} = 17.8 \text{ lbf}$
 - $D_{Stage 2} = 26.3 \text{ lbf}$
 - $Re = 7.31 \times 10^7$ (turbulent)
 - Low drag at peak speed
- Rocket Specs
 - Length = 158.85 "
 - Diameter = 6.17'
 - Wetted Area: 21.38 ft^2
- Thrust Context:
 - 44.1 lbf drag = 4.6% of the 950 lbf thrust.
 - 26.3 lbf drag = 2.6% of the 950 lbf thrust

- Equations

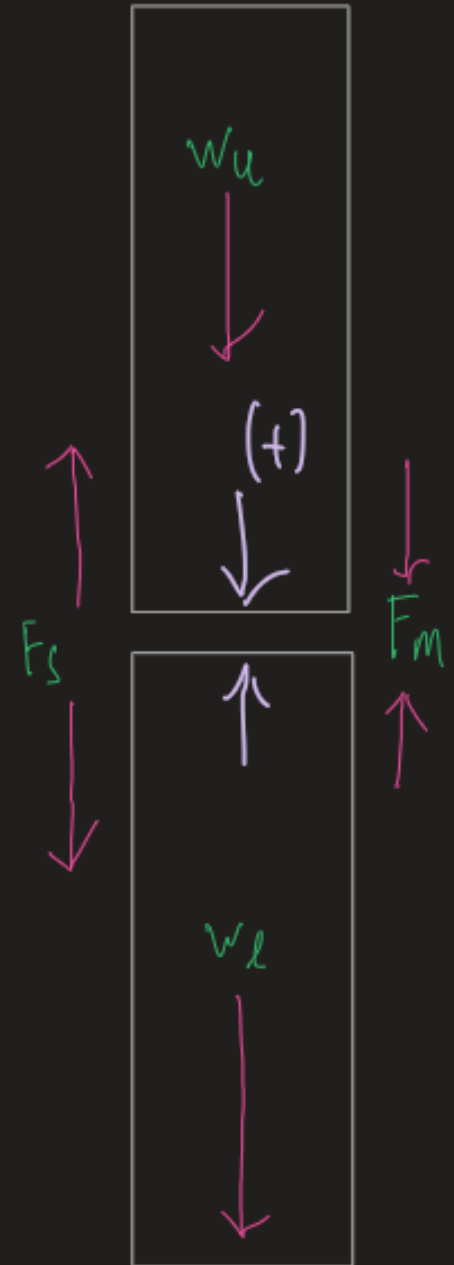
- $D = \left(\frac{1}{2}\right) \rho v^2 C_f A$
- $v = 2008 \frac{\text{ft}}{\text{s}}$
- $\rho = 0.02747 \frac{\text{lb}}{\text{ft}^3}$
- $C_f = 0.00119$ (smooth finish)
- $A = 21.38 \text{ ft}^2$
- $Re = \frac{\rho v L}{\mu}$
- $L = 13.27 \text{ ft}, 5.5 \text{ ft}, 7.7 \text{ ft}$
- $\mu = 3.12 \times 10^{-7} \frac{\text{lb}}{\text{ft}}$

Dynamic Analysis

- Four points will be considered:
 - Before launch at rest, with no normal force.
 - During launch with thrust force greater than zero.
 - During launch with no thrust force, & before separation.
 - During launch, at point of separation.

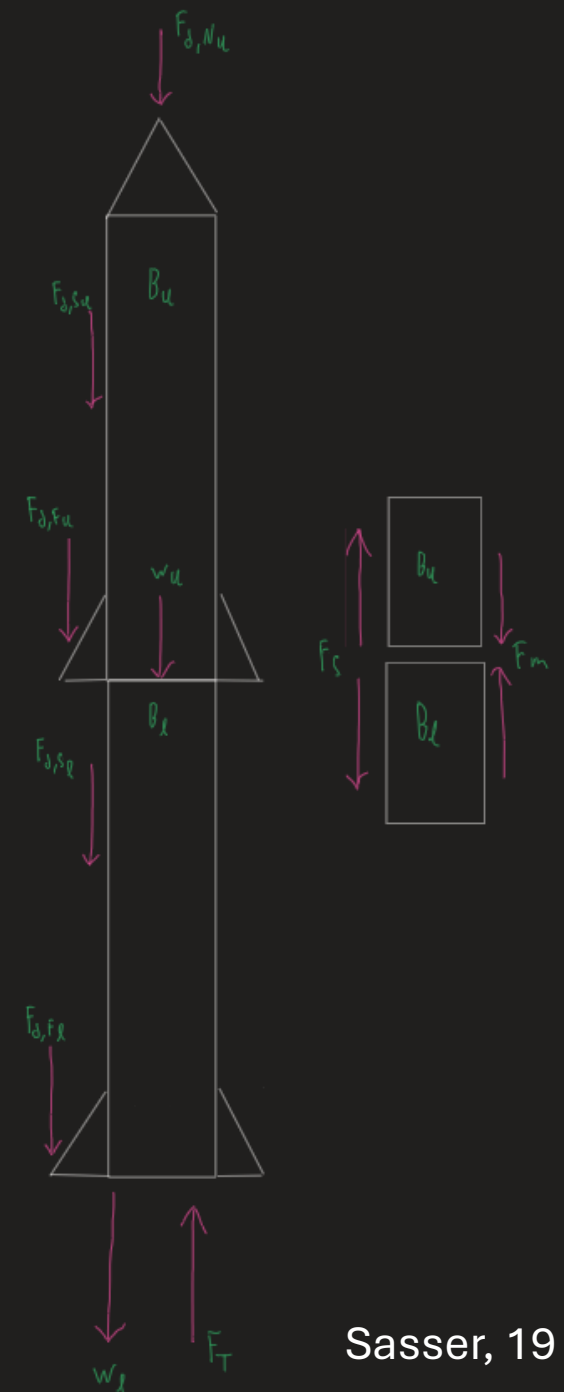
Dynamic Separation Analysis

- Before launch at rest, with no normal force:
 - Drag force, thrust force are zero.
 - Only existing forces are weight, magnetic, and spring.
- $F_m + W_u \geq F_s + W_l$
 - This results in maintaining connection.



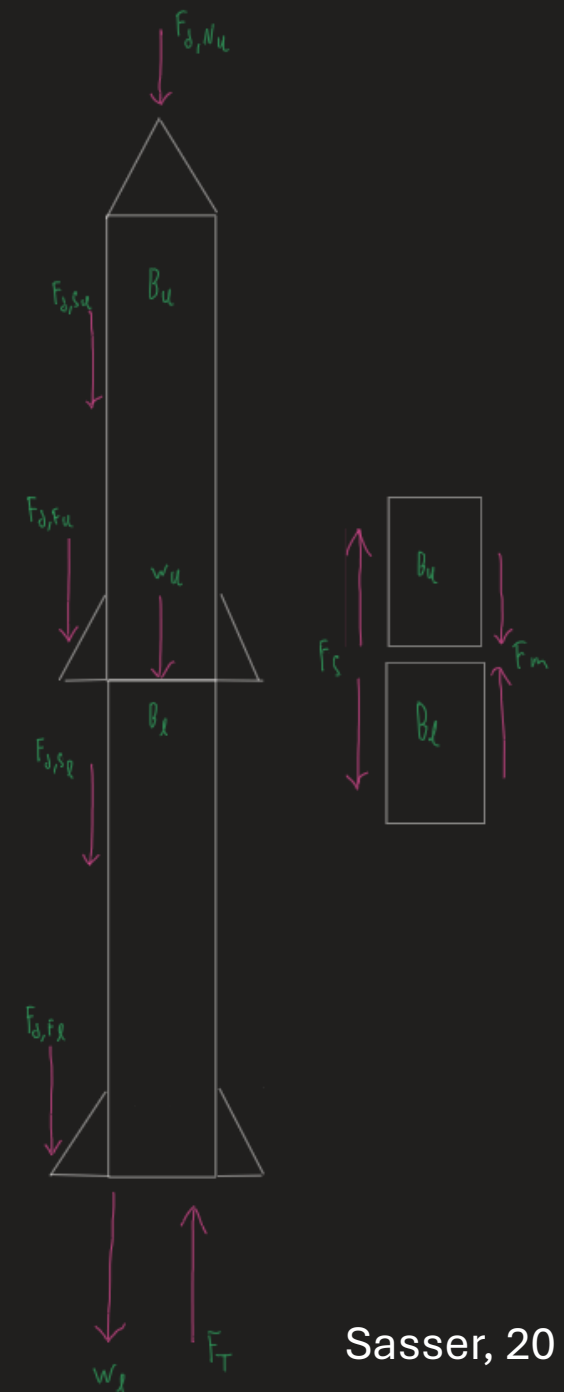
Dynamic Separation Analysis

- During launch with thrust force greater than zero.
- Upper and Lower Drag Forces:
 - $F_{d,U} = F_{d,N} + F_{d,S1} + F_{d,F1}$
 - $F_{d,L} = F_{d,S2} + F_{d,F2}$
- Analyzing for connection between stages:
 - $ma = 0$ at separation point relative to the rocket.
 - Positive is compression.
 - $F_T + F_{d,U} + W_u + F_m \geq F_s + F_{d,L} + W_l$
- When Thrust force is over:
 - $F_{d,U} + W_u + F_m \geq F_s + F_{d,L} + W_l$
 - To maintain connection



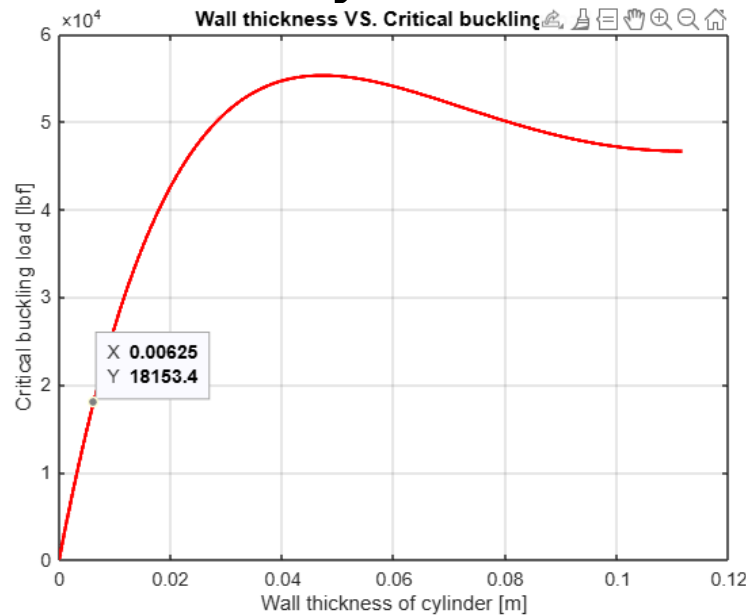
Dynamic Separation Analysis

- During launch at separation point:
 - When F_m is switched to act in tension.
 - Positive is in tension.
 - $F_m + F_s + F_{d,L} + W_l > F_{d,U} + W_u$
- This equation results in separation.
- These equations will be accurately calculated when separation altitude window is identified.



Bob's Analysis

- [1]
- Separation device buckling analysis method 1: Used analysis to determine the use of Euler column analysis. Performed Euler column analysis by hand to determine critical buckling load
 - Separation device buckling analysis method 2: used Euler column analysis with $P_{cr}=1000$ [lbf] and solved for inner diameter



```
1 function[Pcr]= Changing_inner_diameter(di)
2 %Computes critical buckling load of separation device
3 % Inputs: inner and outer diameters (respectfully)
4 Do= 0.11166; % [m] (outer diameter acquired from CAD)
5 C= 1; % [unitless] (end condition constant)
6 E= 69e9; % [Pa] (young's modulus)
7 L= 0.1397; % [m] (length acquired from CAD files)
8 A= pi*((Do/2)^2)-((di/2)^2); % [m^2]
9 I= (pi/64)*((Do^4)-(di^4)); % [m^4]
10 k= I/A; % [m]
11 Pcr=((A*(C*(pi^2)*E))/(((L/k)^2)))*(0.224809); % [lbf]
12 end
```

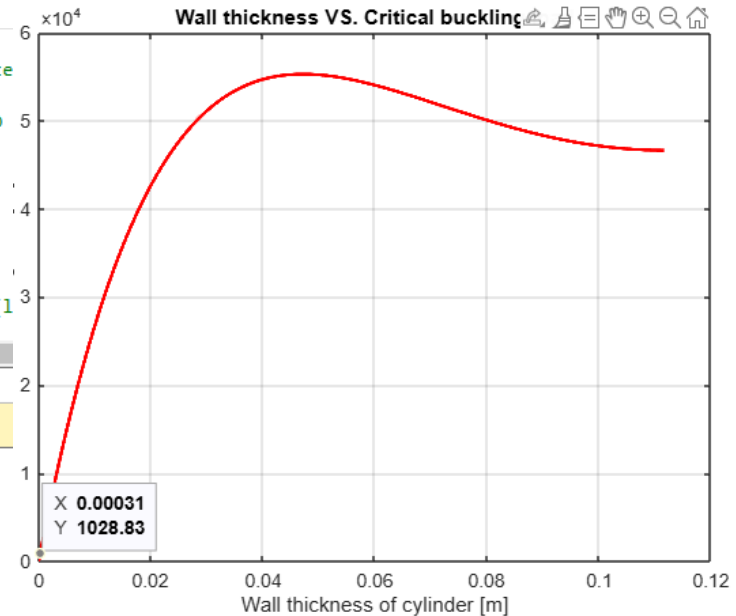
Command Window

New to MATLAB? See resources for [Getting Started](#).

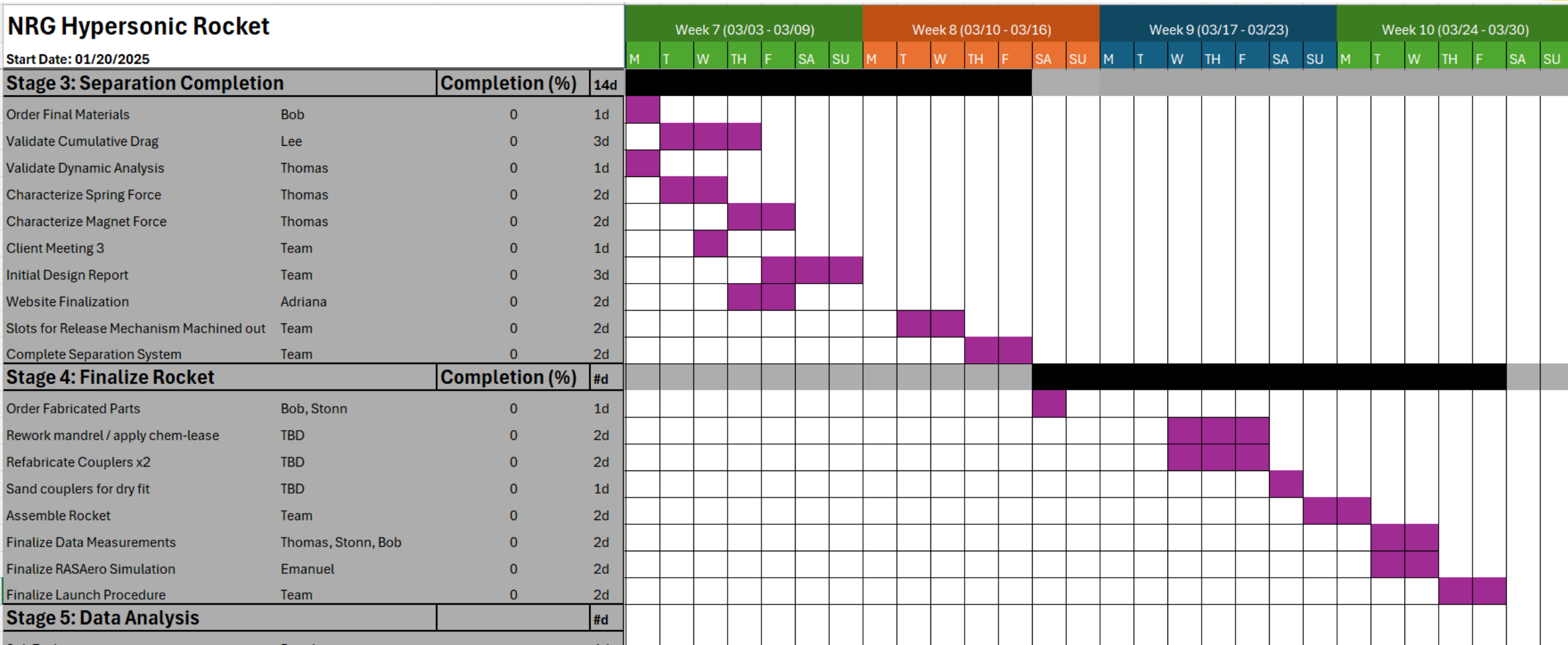
>> Changing_inner_diameter(0.10541)

ans =

18.1534202949223e+003



Gantt Chart



Budget

- The budget for our project is \$5000, \$0 have been spent but we are planning to buy the drogue and main parachutes soon (estimates shown below).
- We have raised \$700 on GoFundMe so far

	Description:	Amount [\$]:
Available funding -	Northrop Grumman funding	+\$5,000
Donations -	GoFundMe	+\$700
Current Expenses -	N/A	-\$0
In-progress expenses -	N/A	-\$0
Upcoming expenses -	36" DROGUE CHUTE [2]	-\$236.34
	144" MAIN CHUTE [2]	-\$770
Net Balance:		\$4,693.66 (after upcoming expenses)

Bill of Materials (BoM)

Line Number	Item	Description	Quantity	Unit Cost	Total Cost	Need Date	Order By Date	Date Ordered	Date Received	Grand Total	
1	Magnets	40 lbf	2	\$10.00	\$20.00	3/1/2025	2/15/2025	2/10/2025	2/24/2025		\$3,544.32
2	Booster	N3300R	2	\$1,153.99	\$2,307.98	Nov-25	Aug-25	N/A	M/A		
3	Carbon Fiber	Material	TBD	Donated	Nothing	Aug-25	N/A	N/A	N/A		
4	Honey comb Core	Standard CetaAramid Honeycomb is a lightweight, high strength, nonmetallic honeycomb core material used to add stiffness in weight critical applications 24"x48"	2	\$155	\$310	25-Aug	N/A	N/A	N/A		
5	Parachutes	36-in Drogue Parachutes	2	\$118.17	\$136.34	4/20/2025	4/1/2025	N/A	N/A		
6	Parachutes	144-in Main Chute	2	\$385	\$770	4/20/2025	4/1/2025				
7											
8											
9											
10											

Conclusion

- Next Steps:
 - Machine out slots in separation system.
 - Characterize spring and magnet force.
 - Solve for Acceleration to determine accurate kinematics.
 - Finalize RASAero simulation.

References

- [1] R. Budynas and K. Nisbett, *Shigley's Mechanical Engineering Design*. McGraw-Hill, 2014.
- [2] The Engineering ToolBox, "Young's Modulus - Tensile and Yield Strength for common Materials," *Engineeringtoolbox.com*, 2003. https://www.engineeringtoolbox.com/young-modulus-d_417.html
- [3] ACP Composites, "Aramid Honeycomb Core - Standard Cell", 2025 <https://acpcomposites.com/shop/core-materials/honeycomb-core/aramid-honeycomb-core-standard-cell>
- [4] "Aerotech N3300R-PS RMS-98/15360 reload kit (1 pack) - 14330P," AeroTech/Quest Division, RCS Rocket Motor Components, Inc, https://aerotech-rocketry.com/products/product_4a713877-dd26-42a3-82a2-adf6b4b498f1 (accessed Mar. 3, 2025).